

Sample-Conditioned Hypothesis Stability Sharpens Information-Theoretic Generalization Bounds

Background

- Learning algorithm $\mathcal{A}: S \to W$ i.e. mapping a training sample to a hypothesis.
- Gen. Err. = \mathbb{E} [Test Err. Train Err.] \leq Gen. Bound.
- Information-theoretic (IT) bounds belong to the class of Gen. Bound.

Limitations of IT Generalization bounds

- Original input-output mutual information (IOMI) (e.g., I(W; S) in [5]) based bound can $\rightarrow \infty \approx$.
- \implies solved by conditional mutual information (CMI) $I(W; U|\widetilde{Z})$ in [4] \bowtie .
- Slow convergence rate, e.g., $\mathcal{O}(1/\sqrt{n}) \cong \longrightarrow$ mitigated by [3, 6] and so on \mathfrak{S} .
- Non-vanishing in Stochastic Convex Optimization (SCO) problems $[2] \odot$

Contributions

Our contribution: Incorporating stability-based analysis into IT framework which improves both stability-based bounds and IT bounds.

Key Observation from Algorithmic Stability

• Given $S = \{Z_i\}_{i=1}^n$ and Z'_i :

- $\begin{vmatrix} Z_1, \dots, |Z_i| & \dots, Z_n \xrightarrow{\mathcal{A}} |W| \Rightarrow \text{Loss of } (W, Z) \\ Z_1, \dots, |Z_i'| & \dots, Z_n \xrightarrow{\mathcal{A}} |W^{-i}| \Rightarrow \text{Loss of } (W^{-i}, Z) \end{vmatrix}$
- \mathcal{A} is Stable \iff Loss of (W^{-i}, Z) is close to Loss of (W, Z). • Uniform Stability [1]:
- $\sup_{W,W^{-i},Z} \left| \text{Loss of } (W,Z) \text{Loss of } (W^{-i},Z) \right| \leq \text{Unif. Stability Param.}$ • Sample-Conditioned Hypothesis (SCH) Stability in this paper $\mathbb{E}_{W,W^{-i}}\left[\sup_{Z} \left| \text{Loss of } (W,Z) - \text{Loss of } (W^{-i},Z) \right| \right] \leq \text{SCH Stability Param.},$

Some terminologies

• Evaluated Data $Z \in (Z_i, Z'_i)$;

where Z can be either Z_i or Z'_i .

- (Neighboring) Hypothesis pair: (W, W^{-i})
- Membership: e.g. 1{Evaluated Data = Z_i }

Main Theorem (informal.)

If \mathcal{A} is stable, then

Gen. Err. \preceq Stability Param $\times \sqrt{I}$ (Evaluated Data; Membership|Hypothesis Pair)

New CMI

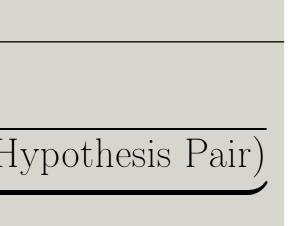
Generalization, in this context, pertains to the ability to infer, given (W, W^{-i}) and Evaluated Data, whether the Evaluated Data corresponds to Z_i or Z'_i .

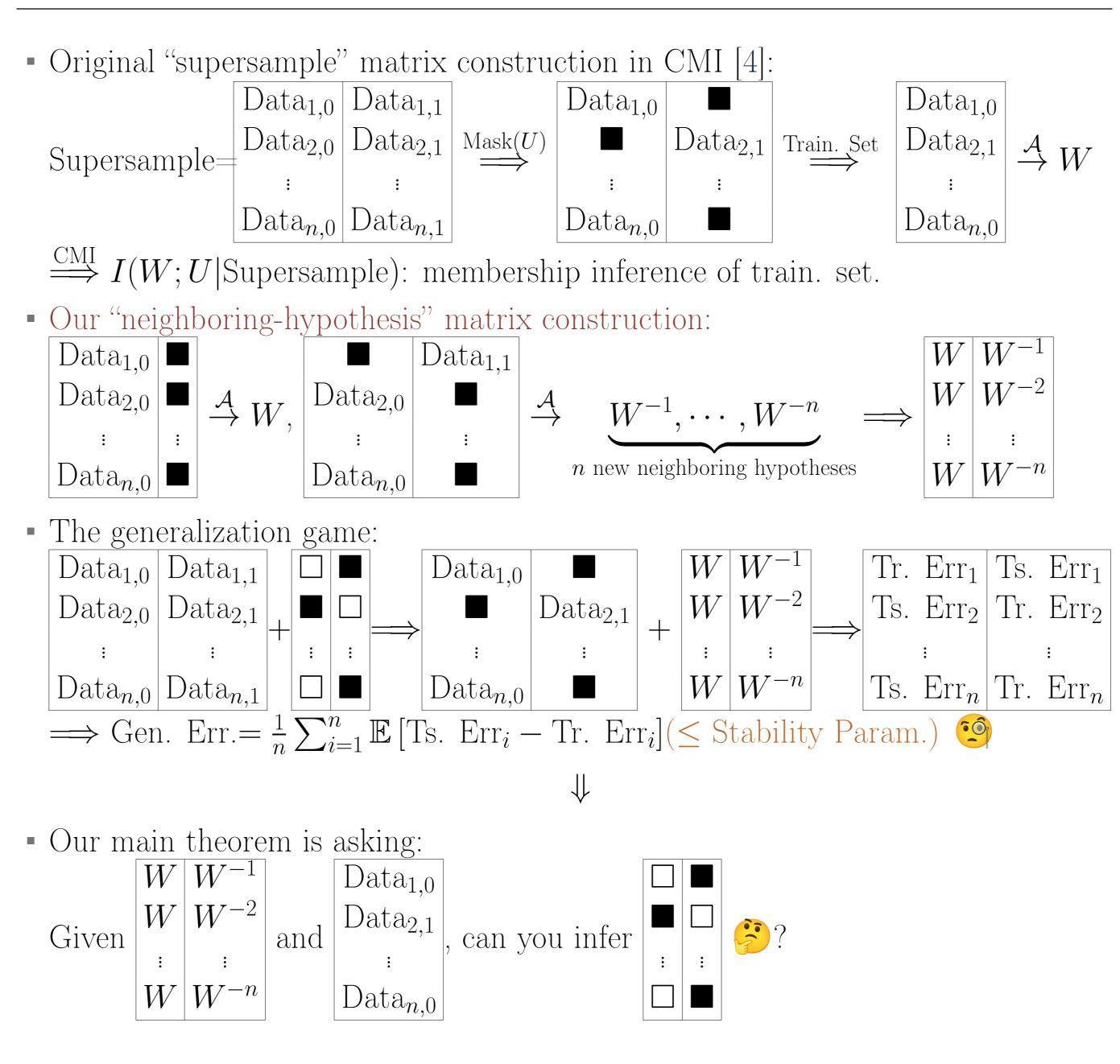
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Novel Construction: "Neighboring-Hypothesis" Matrix







More Technical? All about Bounding CGF

Recall Donsker-Varadhan (DV) lemma:

Gen. Err. $\leq \inf_{t>0} \frac{\text{IOMI or CMI} + \text{CGF}}{+}$.

Let $f_{\rm DV}$ be so-called DV auxiliary function, then $CGF = \log \mathbb{E} \left[\exp \left(t \cdot f_{DV} \right) \right] \leq Some Concentration Bound.$

• Typical choices of f_{DV} in previous works:

Single Loss of (w, z') $f_{\rm DV} = \begin{cases} \text{Loss of } (w, z') - \text{Expected Loss of } (w, Z') \\ \text{Loss of Data 1} - \text{Loss of Data 2 for the same } w \end{cases}$

where in the last choose, Data 1 is chosen uniformly from a data pair, e.g., (Z^0, Z^1) , decided by a $U \sim \text{Bern}(1/2) \Longrightarrow \text{Data } 1 = Z^U$, Data $2 = Z^{1-U}$. • In this paper:

 $f_{\rm DV} = \begin{cases} \text{Loss of } (w, z') - \text{Conditional Expected Loss of } (W^{-i}, z') \\ \text{Loss of Hypothesis 1 - Loss of Hypothesis 2 for the same } z \end{cases},$ where in the last choose, Hypothesis 1 is chosen uniformly from a neighboring hypothesis pair, e.g., (W^0, W^1) , decided by a $U \sim \text{Bern}(1/2)$ \implies Hypothesis $1 = W^U$, Hypothesis $2 = W^{1-U}$.

Application: Stochastic Covex Optimization Problems

SCO setting: Hypothesis set is convex; Objective function is convex.

problems) given by [2]:

Gen. Err. $\leq \mathcal{O}(1/\sqrt{n})$. , where α usually satisfies

- Previous IOMI or CMI bound: $\mathcal{O}\left(\alpha\sqrt{\frac{\text{IOMI or CMI}}{n}}\right)$
- that CGF $\leq \frac{t^2 \alpha^2}{2}$. e.g., α can be a SubGaussian variance proxy or

$$\alpha = \sup_{\text{Hypothesis, Data}}$$

• [2] shows that $\alpha = \mathcal{O}(1)$ (=Lip. Param.×Diam. of Hypothesis Domain) and Previous IOMI \geq Previous CMI = $\mathcal{O}(n)$.

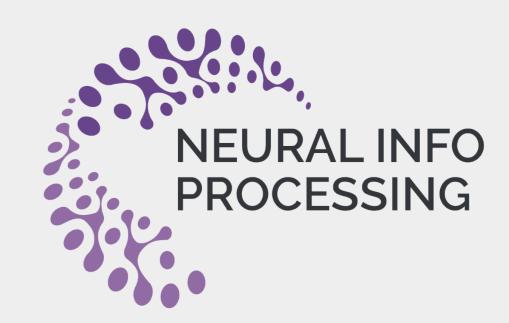
$$\Longrightarrow \mathcal{O}\left(\alpha\sqrt{\frac{\text{IOMI or CMI}}{n}}\right) \in \mathcal{O}$$

- Our new CMI bound: Stability Param. = $\mathcal{O}(1/\sqrt{n})$ and New CMI= $\mathcal{O}(1)$.
- IOMI or CMI 😕?

Concluding Remarks

- Problem Contexts.
- the original CMI in a broader context remains an open question.
- 499-526, 2002.

- Conference on Learning Theory. PMLR, 2020.
- Advances in Neural Information Processing Systems, 2017



• In convex-Lipschitz-bounded (CLB) counterexamples (which is a subset of SCO

|Loss of Data 1 - Loss of Data 2|.

 $\mathcal{O}(1) \Longrightarrow$ Fail to explain the learnability 2.

 \implies New CMI Bound $\in \mathcal{O}(1/\sqrt{n}) \Longrightarrow$ Can explain the learnability $\mathfrak{S}!$ • Wait, Stability Param. itself can serve as a generalization bound, why do we need

There is another CLB example in our paper where Stability Param. $= \mathcal{O}(1/\sqrt{n})$ but Gen. Err. \leq New CMI Bound $= \mathcal{O}(1/n)$ \mathfrak{G} Check it!

Take-Home Message: Selecting the Suitable DV Auxiliary Function for Varied

There are additional choices for SCH stability, allowing us to establish connections with the Bernstein condition or achieve faster-rate bounds in certain cases. Our new CMI maintains the same expressiveness as the original CMI and preserves its boundedness property. The comparison between the new CMI and

References

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[2] Mahdi Haghifam, Borja Rodríguez-Gálvez, Ragnar Thobaben, Mikael Skoglund, Daniel M Roy, and Gintare Karolina Dziugaite. Limitations of information-theoretic generalization bounds for gradient descent methods in stochastic convex optimization. In International Conference on Algorithmic Learning Theory, pages 663–706. PMLR, 2023.

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