

# Tighter Information-Theoretic Generalization Bounds from Difference Differenc

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- Information-theoretic generalization bounds can be non-vacuous since they are both **distribution-dependent** and **algorithm-dependent bounds**.
- Our contribution: New **Conditional Mutual Information (CMI)** bounds which are **either theoretically or empirically tighter** than previous CMI bounds for the **same supersample** setting.

### Supersample Setting



Let  $\widetilde{Z}$  drawn i.i.d. from  $\mu$  and  $U = (U_1, U_2, \dots, U_n)^T \sim \text{Unif}(\{0, 1\}^n)$ .

$$\begin{aligned} \text{Supersample}\,\widetilde{Z} &= \begin{bmatrix} Z_{1,0} & Z_{1,1} \\ \widetilde{Z}_{2,0} & \widetilde{Z}_{1,1} \\ \vdots & \vdots \\ \widetilde{Z}_{n,0} & \widetilde{Z}_{n,1} \end{bmatrix} \stackrel{}{\longrightarrow} S = \begin{bmatrix} Z_{1,U_1} \\ \widetilde{Z}_{2,U_2} \\ \vdots \\ \widetilde{Z}_{n,U_n} \end{bmatrix} \stackrel{}{\longrightarrow} W \end{aligned}$$
$$\begin{aligned} \text{Err} &\triangleq \mathbb{E}_{W,S} \left[ \mathbb{E}_{Z \sim \mu}[\ell(w, Z)] - \frac{1}{n} \sum_{i=1}^{n} \ell(w, Z_i) \right] = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{W,U_i,\widetilde{Z}} \left[ (-1)^{U_i} \left( \ell(W, \widetilde{Z}_{i,1}) - \ell(W, \widetilde{Z}_{i,0}) \right) \right] \end{aligned}$$

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Lemma (Steinke and Zakynthinou [2020])

Assume the loss is bounded between [0, 1], we have  $|\text{Err}| \leq \sqrt{\frac{2l(W; U|\widetilde{Z})}{n}}$ .

### CMI, f-CMI and e-CMI



• Using the superscripts + and - to replace the 0 and 1: e.g, let  $\widetilde{Z}_i = (\widetilde{Z}_i^+, \widetilde{Z}_i^-)$ 

• 
$$L_i \triangleq (L_i^+, L_i^-) = (\ell(W, \widetilde{Z}_i^+), \ell(W, \widetilde{Z}_i^-))$$

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### **Generalization Bounds via Loss Difference**



#### Theorem

Assume the loss is bounded between [0, 1], we have

$$|\operatorname{Err}| \leq \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{\widetilde{Z}} \sqrt{2I^{\widetilde{Z}}(\Delta L_{i}; U_{i})} \leq \frac{1}{n} \sum_{i=1}^{n} \sqrt{2I(\Delta L_{i}; U_{i}|\widetilde{Z})},$$

$$|\operatorname{Err}| \leq \frac{1}{n} \sum_{i=1}^{n} \sqrt{2I(\Delta L_{i}; U_{i})}.$$

$$(1)$$

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Estimating  $I(W; U_i | \tilde{Z}_i)$  vs  $I(\Delta L_i; U_i)$ :

- W is a high-dimensional R.V.
- $\Delta L_i$  is an one-dimensional R.V.  $\Longrightarrow$  Easy-to-Compute!

### **A Communication View of Generalization**





Figure: Channel from  $U_i$  to  $\Delta L_i$ . Zero-one loss assumed.

#### Theorem

Under <u>zero-one</u> loss and for any <u>interpolating</u> algorithm  $\mathcal{A}$ ,  $I(\Delta L_i; U_i) = (1 - \alpha_i) \overline{\ln 2}$  nats for each *i*, and  $|\text{Err}| = L_{\mu} = \sum_{i=1}^{n} \frac{I(\Delta L_i; U_i)}{n \ln 2}$ .

⇒ Generalization error is exactly determined by the communication rate over the channel in the figure averaged over all such channels.



Key observation:

$$\operatorname{Err} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{W,U_{i},\widetilde{Z}} \left[ (-1)^{U_{i}} \left( \ell(W,\widetilde{Z}_{i}^{+}) - \ell(W,\widetilde{Z}_{i}^{-}) \right) \right] = \frac{2}{n} \sum_{i=1}^{n} \mathbb{E}_{L_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+} \right], \text{ where } L_{i}^{+} = \frac{1}{n} \sum_{i=1}^{n} \mathbb{E}_{U_{i}^{+},\varepsilon_{i}} \left[ \varepsilon_{i} L_{i}^{+}$$

 $\varepsilon_i = (-1)^{U_i}$  is the Rademacher variable.



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 $\varepsilon_i = (-1)^{\overline{U}_i}$  is the Rademacher variable.

#### Lemma

Consider the weighted generalization error,  $\operatorname{Err}_{\mathcal{C}_1} \triangleq \mathcal{L}_{\mu} - (1 + \mathcal{C}_1)\mathcal{L}_n$ . We have

$$\operatorname{Err}_{C_1} = \frac{2+C_1}{n} \sum_{i=1}^n \mathbb{E}_{L_i^+, \tilde{\varepsilon}_i} \left[ \tilde{\varepsilon}_i L_i^+ \right],$$

where  $\tilde{\varepsilon}_i = (-1)^{\overline{U}_i} - \frac{c_1}{c_1+2}$  is a shifted Rademacher variable with mean  $-\frac{c_1}{c_1+2}$ .



#### Theorem

Let  $\ell(\cdot, \cdot) \in [0, 1]$ . There exist  $\mathcal{C}_1, \mathcal{C}_2 > 0$  such that

$$L_{\mu} \leq (1+C_{1})L_{n} + \sum_{i=1}^{n} \frac{I(L_{i}^{+}; U_{i})}{C_{2}n},$$

$$L_{\mu} \leq L_{n} + \sum_{i=1}^{n} \frac{4I(L_{i}^{+}; U_{i})}{n} + 4\sqrt{\sum_{i=1}^{n} \frac{L_{n}I(L_{i}^{+}; U_{i})}{n}}.$$
(3)
(4)



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#### Faster Rate than Square-Root based Bound

If  $L_n \rightarrow 0$ , then (3)(4) vanish with a faster rate.

### **Sharpness Based MI Bound**



#### Theorem

For any  $\lambda \in (0,1)$ , the " $\lambda$ -sharpness" at position i of the training set is defined as

$$\mathcal{F}_{i}(\lambda) \triangleq \mathbb{E}_{\mathcal{W}, \mathcal{Z}_{i}} \left[ \ell(\mathcal{W}, \mathcal{Z}_{i}) - (1 + \lambda) \mathbb{E}_{\mathcal{W} \mid \mathcal{Z}_{i}} \ell(\mathcal{W}, \mathcal{Z}_{i}) \right]^{2}.$$

Let  $F(\lambda) = \frac{1}{n} \sum_{i=1}^{n} F_i(\lambda)$ . Assume  $\ell(\cdot, \cdot) \in \{0, 1\}$ ,  $\lambda \in (0, 1)$ . Then, there exist  $C_1, C_2 > 0$  such that

$$\operatorname{Err} \leq C_1 F(\lambda) + \sum_{i=1}^n \frac{I(L_i^+; U_i)}{C_2 n}.$$
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(5)

- $L_n = 0 \rightarrow F(\lambda) = 0$ , but  $L_n = 0 \nleftrightarrow F(\lambda) = 0$ ;
- For any fixed  $C_1$  and  $C_2$ , Eq. (5) is tighter than Eq. (3).

### **Experiments**







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## **Thank You!**